

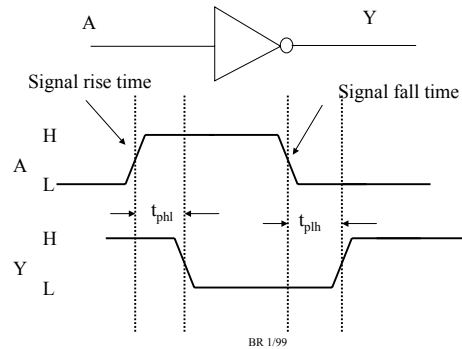
## Gate Delay

- Transistors within a gate take a finite amount of time to switch. This means that a change on the input of a gate takes a finite amount of time to cause a change on the output.
- This time is known as **Propagation Delay**
- Smaller transistors means faster switching times. Semiconductor companies are continually finding new ways to make transistors smaller, which means transistors are faster, and more can fit on a die in the same area.

BR 1/99

1

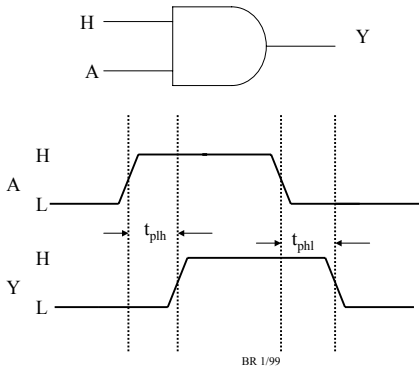
## Propagation Delay (inverting)



BR 1/99

2

## Propagation Delay (non inverting)



BR 1/99

3

## Propagation Delay Definitions

- $t_{pLH}$  -- time between a change in an input and a low to high change on the output. Measured from 50% point on input signal to 50% point on the output signal. The 'lh' part (low to high) refers to OUTPUT change, NOT input change
- $t_{pHL}$  -- time between a change in an input and a high to low change on the output. Measured from 50% point on input signal to 50% point on the output signal. The 'hl' part (high to low) refers to OUTPUT change, NOT input change

BR 1/99

4

## Propagation Delay (non inverting)



Each Input to Output path has its own delay:

$A2Y_{t_{pLH}}$ ,  $A2Y_{t_{pHL}}$ ,  $B2Y_{t_{pLH}}$ ,  $B2Y_{t_{pHL}}$

These delays can be different.

For simplicity, may just assign one delay for entire gate:

$Y_{t_{pd}}$

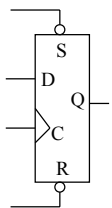
Databooks give typical and maximum propagation delays for combinational outputs.

BR 1/99

5

## DFF Timing

- Propagation Delay
  - C2Q: Q will change some propagation delay after change in C. Value of Q is based on D input for DFF.
  - S2Q, R2Q: Q will change some propagation delay after change on S input, R input
  - Note that there is NO propagation delay D2Q for DFF!
  - D is a Synchronous INPUT, no prop delay value for synchronous inputs



BR 1/99

6

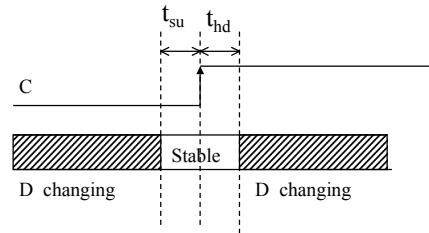
## Setup, Hold Times

- Synchronous inputs (e.g. D) have Setup, Hold time specification with respect to the CLOCK input
- Setup Time: the amount of time the synchronous input (D) must be *stable before* the active edge of clock
- Hold Time: the amount of time the synchronous input (D) must be *stable after* the active edge of clock.

BR 1/99

7

## Setup, Hold Time



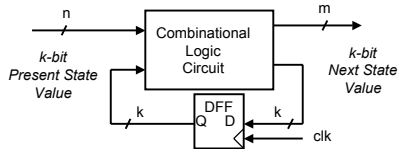
If changes on D input violate either setup or hold time, then correct FF operation is not guaranteed.

Setup/Hold measured around active clock edge.

BR 1/99

8

## Sequential System Timing



Question: What is the MAXIMUM frequency of operation of this system?

Maximum Frequency =  $1 / (\text{longest delay path})$

What are longest paths???

BR 1/99

9

## Longest Paths in Sequential System Diagram

Paths to check:

- Clock to Output delay:  $T_{c2q} + T_{\text{comb\_Q2O}}$  max  
 $T_{\text{comb\_Q2O}}$  is longest path from Q output to any output
- Register to Register delay:  $T_{c2q} + T_{\text{comb\_Q2D}}$  max +  $T_{\text{setup}}$   
 $T_{\text{comb\_Q2D}}$  is longest path from Q dff output to D dff input
- Pin to Pin combinational delay:  $T_{\text{comb\_I2O}}$  max  
 (input pin to output pin, no intervening registers)

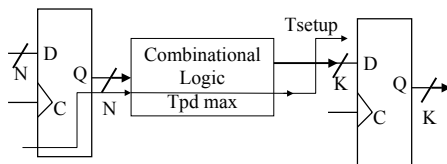
Typically, path "B" is the worst case.

BR 1/99

10

## Inputs/Outputs Registered

Very often, all inputs and outputs are registered. Then register-to-register delay will almost always determine maximum frequency.

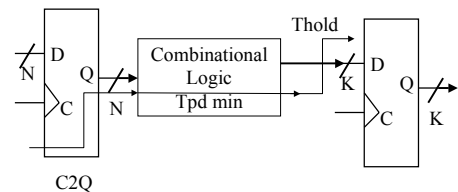


$$\text{delay} = T_{c2q} + T_{pd \text{ max}} + T_{\text{setup}}$$

BR 1/99

11

## Hold Time and Shortest Paths



To satisfy hold time:

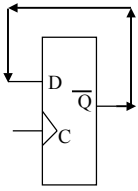
$$T_{c2q} + T_{pd \text{ (minimum)}} \geq T_{\text{hold}}$$

This is normally easily satisfied in a sequential system.

BR 1/99

12

## Toggle Frequency



$$\text{toggle frequency} = 1 / (C2Q + T_{\text{setup}})$$

assume wire delay is negligible

What about setup time?

$$T_{c2q} + T_{pd}(\min) \geq \text{Thold}$$

$$T_{cq} > \text{Thold}$$

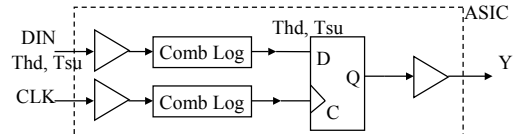
assuming zero wire delay

BR 1/99

13

## Setup, Hold Time for External Inputs

External inputs are buffered through pad drivers and may go through combinational logic before they reach a synchronous input. This buffering adds propagation delay. How does this propagation delay affect the EXTERNAL setup and hold time????

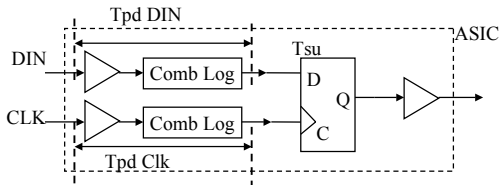


What is Thd, Tsu for DIN? It is NOT the same as for Thd, Tsu of the internal D FF!!!!!! Thd, Tsu for DIN is specified in the DATASHEET for design.

BR 1/99

14

## Calculating External Setup times



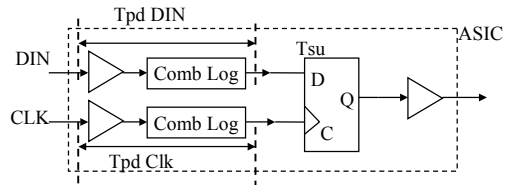
Worst case setup time for DIN occurs when 'DIN' is **DELAYED** relative to CLK. Means clock edge arrives early, requiring DIN to be ready sooner.

$$\text{Din Setup} = T_{su} + T_{pd \text{ DIN}}(\max) - T_{pd \text{ CLK}}(\min)$$

BR 1/99

15

## Calculating External Hold times



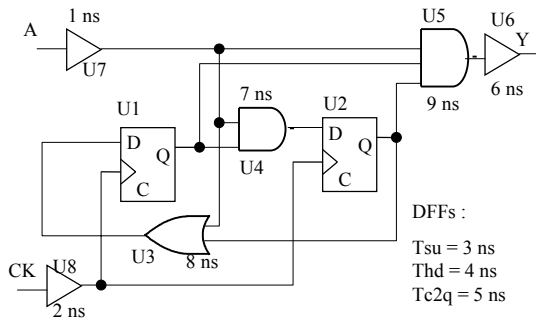
Worst case hold time for DIN occurs when 'CLK' is **DELAYED** relative to DIN. Means clock edge arrives late, requiring DIN to hold its value longer.

$$\text{Din Hold} = T_{hd} + T_{pd \text{ CLK}}(\max) - T_{pd \text{ DIN}}(\min)$$

BR 1/99

16

## A Timing Example



BR 1/99

17

## Timings

Max Register to Register Delay

$$U2 T_{c2q} + U3 T_{pd} + U1 T_{su} = 5 + 8 + 3 = 16 \text{ ns.}$$

$$\begin{aligned} \text{A setup time} &= T_{su} + A2D T_{pd \text{ max}} - \text{Clk } T_{pd \text{ min}} \\ &= T_{su} + (T_{pd \text{ U3}} + T_{pd \text{ U7}}) - T_{pd \text{ U8}} \\ &= 3 + (8 + 1) - 2 = 10 \text{ ns} \end{aligned}$$

$$\begin{aligned} \text{A hold time} &= T_{hd} + \text{Clk } T_{pd \text{ max}} - A2D T_{pd \text{ min}} \\ &= T_{hd} + T_{pd \text{ U8}} - (T_{pd \text{ U4}} + T_{pd \text{ U7}}) \\ &= 4 + 2 - (7 + 1) = -2 \text{ ns} \end{aligned}$$

BR 1/99

18

## Timings (Cont)

Clock to Out

$$= U8 \text{ Tpd} + U2 \text{ Tc2q} + U5 \text{ Tpd} + U6 \text{ Tpd}$$

$$= 2 + 5 + 9 + 6 = 22 \text{ ns}$$

Pin to Pin Combinational Delay (A to Y)

$$= U7 \text{ Tpd} + U5 \text{ Tpd} + U6 \text{ Tpd}$$

$$= 1 + 9 + 6 = 16 \text{ ns}$$

Max Clock Freq =  $1 / \text{Max (Reg2reg, Clk2Out, Pin2Pin)}$

$$= 1 / \text{Max (16, 22, 16)}$$

$$= 45.5 \text{ Mhz}$$

BR 1/99

19

## DataSheet

Parameter	Description	Min	Max	Units
Tclk	Clock Period	22		ns
Fclk	Clock Frequency		45.5	Mhz
Atsu	A setup time	10		ns
Athd	A hold time	-2		ns
A2Y	A to Y Tpd		16	ns
Ck2Y	Clock to Y tpd		22	ns

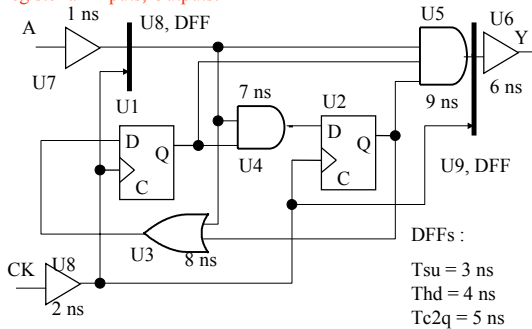
Negative hold times are typically specified as 0 ns.

BR 1/99

20

## How do we improve timings?

Register all Inputs, Outputs!



BR 1/99

21

## New Timings

Max Register to Register Delay

$$U2 \text{ Tc2q} + U5 \text{ Tpd} + U9 \text{ Tsu} = 5 + 9 + 3 = 17 \text{ ns.}$$

A setup time =  $T_{su} + A2D \text{ Tpd max} - \text{Clk Tpd min}$

$$= T_{su} + (\text{Tpd U7}) - \text{Tpd U8}$$

$$= 3 + (1) - 2 = 2 \text{ ns}$$

A hold time =  $T_{hd} + \text{Clk Tpd max} - A2D \text{ Tpd min}$

$$= T_{hd} + \text{Tpd U8} - (\text{Tpd U7})$$

$$= 4 + 2 - (1) = 5 \text{ ns}$$

BR 1/99

22

## New DataSheet

Parameter	Description	Min	Max	Units
Tclk	Clock Period	17		ns
Fclk	Clock Frequency		58.8	Mhz
Atsu	A setup time	2		ns
Athd	A hold time	5		ns
Ck2Y	Clock to Y tpd		13	ns

Most designs have all inputs, outputs registered.

BR 1/99

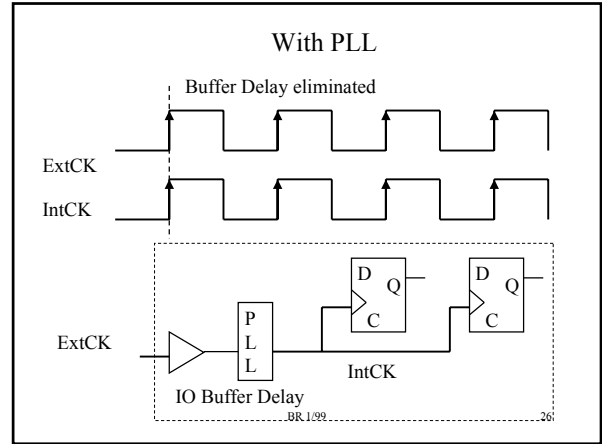
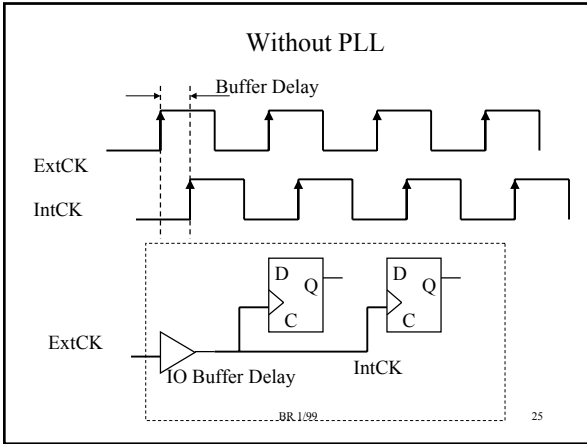
23

## How does a PLL/DLL help?

- A Phased Locked Loop or Delay Locked Loop circuit is used to align the external clock edge at the pin with the internal clock edges at the DFF clk pins
  - Some clock skew due to clock routing network from PLL will still be present, but input buffer delay eliminated.
- This means that we can drop out the Clk Tpd term from the equations
- How does this change things?

BR 1/99

24



### New Timings (PLL, Inputs/Outputs Reg)

Max Register to Register Delay  
 $U2 Tc2q + U5 Tpd + U9 Tsu = 5 + 9 + 3 = 17 \text{ ns.}$

A setup time =  $Tsu + A2D Tpd \text{ max} - \text{Clk Tpd min}$   
 $= Tsu + (Tpd U7) - 0 \text{ (due to PLL)}$   
 $= 3 + (1) - 0 = 4 \text{ ns}$

A hold time =  $Thd + \text{Clk Tpd max} - A2D Tpd \text{ min}$   
 $= Thd + 0 \text{ (due to PLL)} - (Tpd U7)$   
 $= 4 + 0 - (1) = 3 \text{ ns}$

BR 1/99 27

### New Timings (PLL, Inputs/Outputs Reg)

Clock to Out  
 $= U8 Tpd + U9 Tc2q + U6 Tpd$   
 $= 0 \text{ (due to PLL)} + 5 + 6 = 11 \text{ ns}$

NO pin to Pin combinational delay! All inputs/outputs registered!

Max Clock Freq =  $1 / \text{Max (Reg2reg, Clk2Out, Pin2Pin)}$   
 $= 1 / \text{Max (17, 11, 0)}$   
 $= 58.8 \text{ Mhz}$

BR 1/99 28

### New DataSheet (PLL, Inputs/Outputs Reg)

Parameter	Description	Min	Max	Units
Tclk	Clock Period	17		ns
Fclk	Clock Frequency		58.8	Mhz
Atsu	A setup time	4		ns
Athd	A hold time	3		ns
Ck2Y	Clock to Y tpd		11	ns

Clock to Output improved; important in multiple chip designs. External Setup/Hold times closer to setup/hold times of internal DFFs.

BR 1/99 29

### Chip to Chip Timing Calculation

Need to know external setup/hold times all inputs, clk to out of all outputs, all pin to pin combinational delays.

ASIC = Application Specific Integrated Circuit

BR 1/99 30

## Max Register to Register Delay 2 ASIC System

Assume no pin to pin combinational delays and that inputs/outputs of both ASICs are registered.

For any outputs from ASIC #1 which are Inputs to ASIC #2 find maximum of ASIC #1 Clk to out + ASIC#2 Setup time.

For any outputs from ASIC #2 which are Inputs to ASIC #1 find maximum of ASIC #2 Clk to out + ASIC#1 Setup time.

The maximum of these two times will be the minimum clock period.

BR 1/99

31

## Other Factors that effect Timing

- Voltage: the higher the voltage, the faster that gates switch
- Temperature: the lower the temperature, the faster that gates switch
- Process Technology (transistor gate width). The shorter the transistor gate length, the faster the transistor will switch (I.e. 0.5u process versus 0.35u process).
- In a given process run, may get fast N transistors, fast P transistors, slow N transistors, slow P transistors

BR 1/99

32

## Device Characterization

- Do timing analysis on ASICs at four extreme corners to make sure they meet timing specs under all conditions
- Fastest Case: Fast N transistors, Fast P transistors, High Vdd, Low temperature
- Slowest Case: Slow N transistors, slow P transistors, low Vdd, high temperature
- Other two corners can vary but two possible corners are:
  - Fast N, Slow P, Typical Temperature
  - Slow N, Fast P, Typical Temperature

BR 1/99

33

## Speed Grades

- Databooks often list different **speed grades** for a part at the same temperature
- Simply test parts that come off the fabrication line and see how fast they are
  - Divide the parts into different speed bins
  - For three speed grades, a design goal might be to have 15% of your parts fall in the upper bin, 50% in the middle bin, and 25% in the lower bin.
  - As the process matures, more and more fabricated parts will move into the upper speed bin, at which point you make a new upper speed bin.
  - Obviously, faster parts cost more (and are more profitable)

BR 1/99

34

## Static Path Analysis

- After your gate netlist has been mapped to the FPGA, a timing analysis tool will analyze the paths in the design and compute the timings we have discussed
- The timing analyzer takes into account the routing delays in the physical routing and the speed grade of the part you have mapped to.
  - Because routing can sometimes change somewhat drastically for even small changes, often try run multiple device mappings to try to get a 'good route'.

BR 1/99

35

## Static Timing Analysis Reports

- The static timing analyzer will report the following times
  - Register to Register delays
  - Setup times of all external synchronous inputs
  - Clock to Output delays
  - Pin to Pin combinational delays
- The clock to output delay is usually just reported as simply another pin-to-pin combinational delay
- Timing analysis reports are often pessimistic since they use worst case conditions

BR 1/99

36

## Timing Simulation

- The timings extracted by the Timing analysis tool (routing delays, gate delays for a particular speed grade, etc) are used in the simulation
- It may be tempting to simply ignore the delays reported by the timing analyzer, and simply simulate the design 'at speed' to see if it works.
  - If the design simulates correctly, only means that it works for the particular test vectors that you used!
  - Different test vectors exercise different delay paths - you must use test vectors that exercise the LONGEST paths